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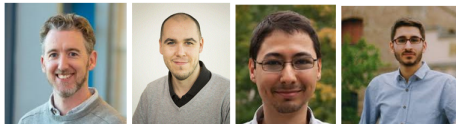
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Introduction to Measurement Error: Prevalence, Impact and Adjustments

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- What is measurement error?
 - Discrepancies between the ‘true’ and the observed value
 - The consequence of a poorly defined construct and/or an imperfect measurement process

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- What is measurement error?
 - Discrepancies between the ‘true’ and the observed value
 - The consequence of a poorly defined construct and/or an imperfect measurement process
- Examples in the Social Sciences
 - Elusive constructs, loosely defined:
 - e.g. happiness, ethnicity, political decentralisation
 - Subjectively elicited data:
 - e.g. survey data, affected by memory failures (*when was the last time you went to a pub?*), social desirability (*for how long have you been unemployed?*)
 - Administrative/official data used as proxies:
 - e.g. using earnings to measure poverty, or measuring violent crime from police records

The Recounting Crime project

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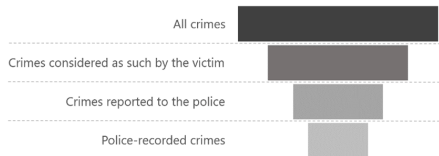
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- Police recorded crime statistics are deeply flawed



- Under-reporting/under-detection of crime
- Recording inconsistencies across forces

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- Why does it matter?
 - We cannot describe reality accurately
e.g. What is the true prevalence of crime in Hong Kong? Has it grown from last year? Is it higher than in Macau?
 - But also, our causal inferences will be biased
e.g. Does unemployment affect crime? Does crime affect mental health?

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e.g. What is the true prevalence of crime in Hong Kong? Has it grown from last year? Is it higher than in Macau?
 - But also, our causal inferences will be biased
e.g. Does unemployment affect crime? Does crime affect mental health?
- There are ways to anticipate the prevalence and impact of measurement error
 - And to some extent adjust for it
 - But to do so we first need to define these errors formally using measurement error models

Defining Measurement Error Formally

- The classical measurement error model (random errors)

$$- \underbrace{X^*}_{\text{observed}} = \underbrace{X}_{\text{true value}} + \underbrace{U}_{\text{noise}}$$

- with the errors taken to be randomly distributed, $U \sim N(0, \sigma_U)$



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$$\underbrace{\text{observed}}_{X^*} = \underbrace{\text{true value}}_X + \underbrace{\text{noise}}_U$$

- with the errors taken to be randomly distributed, $U \sim N(0, \sigma_U)$



- Examples:
 - Recording inconsistencies due to police officers' recall errors
 - Results from a math test
- Only the variance is affected
 - $\sigma_{X^*}^2 = \sigma_X^2 + \sigma_U^2$; but the mean is unaffected since $E(U) = 0$

Systematic Errors

- The classical model is the most commonly used in applications seeking to describe and adjust for measurement error
 - It is simple, and reflects well enough some measurement error mechanisms, but not always

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 - It is simple, and reflects well enough some measurement error mechanisms, but not always
- Measurement error is often *systematic*
 - $X^* = X + U$; but $E(U) \neq 0$



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- Examples:
 - Crime reported to the police
 - Self-reported xenophobia, sexual partners, etc.

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- So far we have assumed that errors are independent
- What if the error is proportional to the true value of the quantity being measured?
 - E.g. memory failures in reporting counts;
How many alcoholic drinks did you have last week?

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- What if the error is proportional to the true value of the quantity being measured?
 - E.g. memory failures in reporting counts;

How many alcoholic drinks did you have last week?
- These can be better specified using a multiplicative rather than an additive model
 - I.e., as $X^* = X \cdot U$, rather than $X^* = X + U$

Multiple Error Mechanisms

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- Often variables are affected by multiple measurement error mechanisms
- This is how we define measurement error in police data
 - *systematic*, since not all crime is reported to the police
 - *random*, subject to variability across areas, as a result of the different recording practices across police forces
 - *multiplicative*, errors seem proportional to the true extent of crime in the area

Multiplicative Errors: Crime Rates

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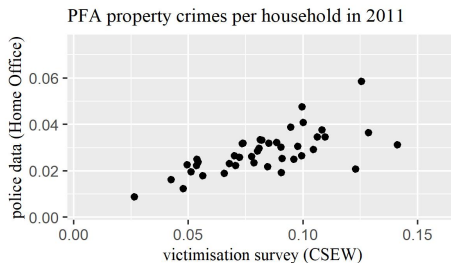
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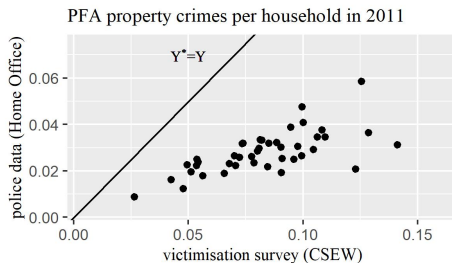
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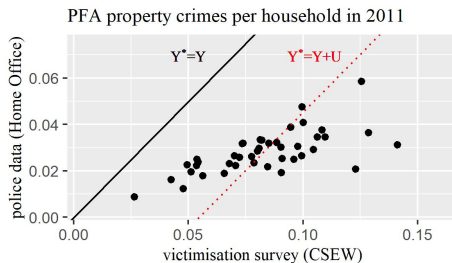
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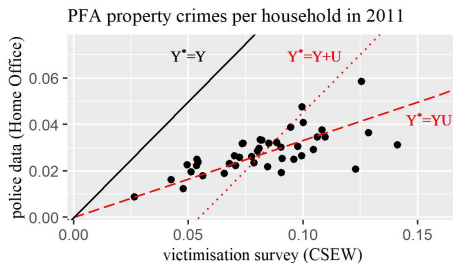
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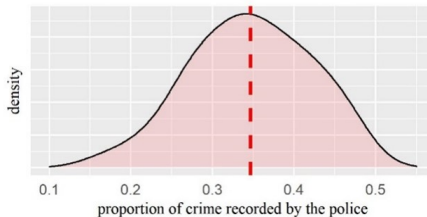
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Measurement error ($U=X^*/X$), property crime



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- We have seen how different forms of measurement error can affect univariate stats
 - Random errors affect measures of dispersion, systematic errors affect measures of centrality
- But how does measurement error affect estimates from multivariate (regression) models?

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 - Random errors affect measures of dispersion, systematic errors affect measures of centrality
- But how does measurement error affect estimates from multivariate (regression) models?
- Assuming only one variable is prone to measurement error, its impact will depend on:
 - ① the outcome model (whether linear, Poisson, etc.)
 - ② the measurement error model (additive, random, etc.)
 - ③ where is the affected variable introduced in the model (as a response or an explanatory variable)

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$$- Y = \alpha + \beta X + \epsilon$$

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- Let's review some scenarios for the case of simple linear regression

$$- Y = \alpha + \beta X + \epsilon$$

- ① Random additive errors affecting the response variable

$$- Y^* = Y + U, \text{ and } U \sim N(0, \sigma_U)$$

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- Let's review some scenarios for the case of simple linear regression

$$Y = \alpha + \beta X + \epsilon$$

- 1 Random additive errors affecting the response variable

$$Y^* = Y + U, \text{ and } U \sim N(0, \sigma_U)$$

- 2 Similar errors affecting the explanatory variable

$$X^* = X + U, \text{ and } U \sim N(0, \sigma_U)$$

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- 2 Similar errors affecting the explanatory variable

$$- X^* = X + U, \text{ and } U \sim N(0, \sigma_U)$$

- 3 Systematic additive errors affecting the response variable

$$- Y^* = Y + U, \text{ and } E(U) \neq 0$$

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$$- Y^* = Y + U, \text{ and } E(U) \neq 0$$

- 4 Systematic multiplicative errors affecting the response variable

$$- Y^* = Y \cdot U, \text{ and } E(U) \neq 1$$

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- 2 Similar errors affecting the explanatory variable

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$$- Y^* = Y + U, \text{ and } E(U) \neq 0$$

- 4 Systematic multiplicative errors affecting the response variable

$$- Y^* = Y \cdot U, \text{ and } E(U) \neq 1$$

- **Question:** Will β be biased in any of those scenarios?

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- Scenario 1: random additive errors on the response
 - $Y^* = \alpha + \beta X + \epsilon$, with $Y^* = Y + U$, and $U \sim N(0, \sigma_U)$

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- Scenario 1: random additive errors on the response
 - $Y^* = \alpha + \beta X + \epsilon$, with $Y^* = Y + U$, and $U \sim N(0, \sigma_U)$
 - $Y + U = \alpha + \beta X + \epsilon$

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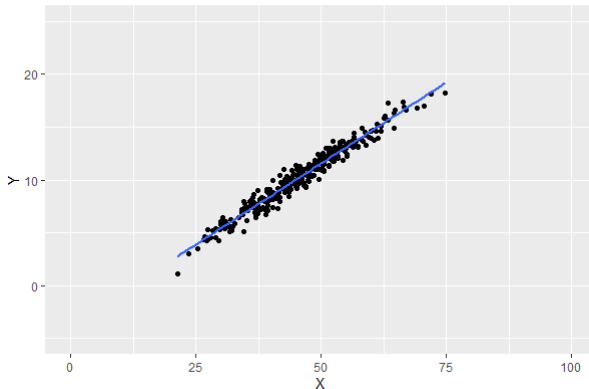
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- Scenario 1: random additive errors on the response
 - $Y^* = \alpha + \beta X + \epsilon$, with $Y^* = Y + U$, and $U \sim N(0, \sigma_U)$
 - $Y + U = \alpha + \beta X + \epsilon$
 - $Y = \alpha + \beta X + (\epsilon - U)$
 - The measurement error is absorbed by the model's error term, affecting precision, but leaving regression coefficients unbiased
 - We can see this effect using simulated data

Classical Error on the Response

Scatterplot for Y and X



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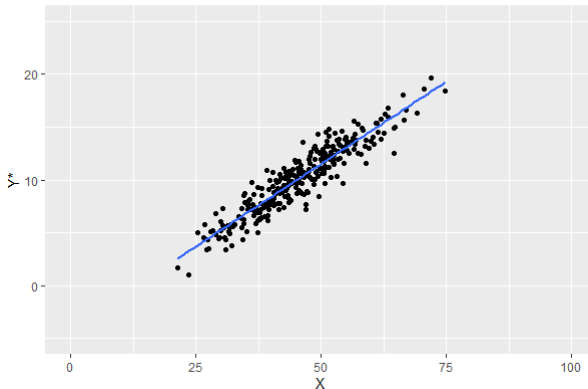
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Scatterplot for Y^* and X , where $Y^*=Y+U$, and $U \sim N(0,1)$



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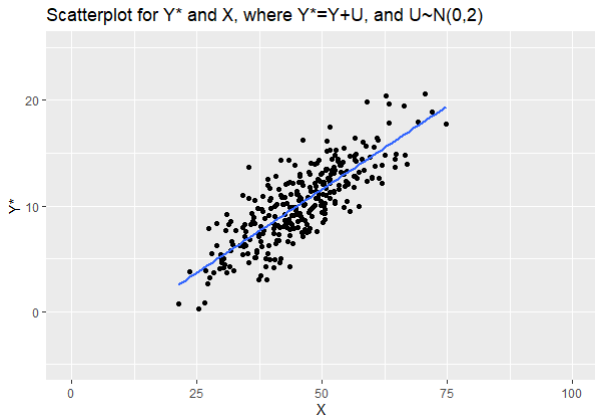
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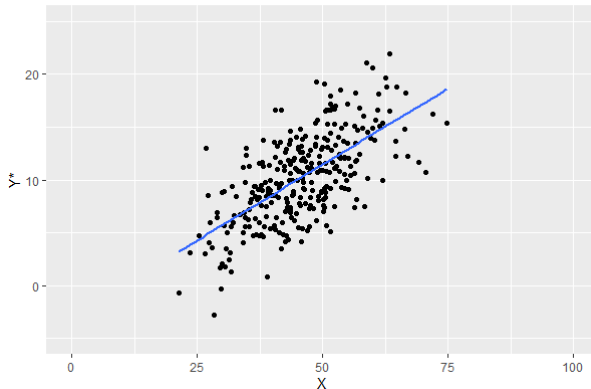
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Scatterplot for Y^* and X , where $Y^*=Y+U$, and $U \sim N(0,3)$



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- Scenario 2: random additive errors on the covariate
 - $Y = \alpha + \beta X^* + \epsilon$, with $X^* = X + U$, and $U \sim N(0, \sigma_U)$

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- Scenario 2: random additive errors on the covariate
 - $Y = \alpha + \beta X^* + \epsilon$, with $X^* = X + U$, and $U \sim N(0, \sigma_U)$
 - Using OLS we can estimate α and β solving...

$$\begin{cases} \hat{\alpha} = \bar{Y} - \hat{\beta} \bar{X} \\ \hat{\beta} = \frac{\sigma_{XY}}{\sigma_X^2} \end{cases}$$

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- If instead we have...

$$\begin{cases} \hat{\alpha}^* = \bar{Y} - \hat{\beta}^* \bar{X}^* \\ \hat{\beta}^* = \frac{\sigma_{X^*Y}}{\sigma_{X^*}^2} \end{cases}$$

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$$\begin{cases} \hat{\alpha}^* = \bar{Y} - \hat{\beta} \bar{X}^* = \bar{Y} - \hat{\beta} \bar{X} = \hat{\alpha}; \quad \underline{\text{unbiased constant}} \\ \hat{\beta}^* = \frac{\sigma_{X^*Y}}{\sigma_{X^*}^2} \end{cases}$$

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- We can see this effect using simulated data

Effect of Random Measurement Error

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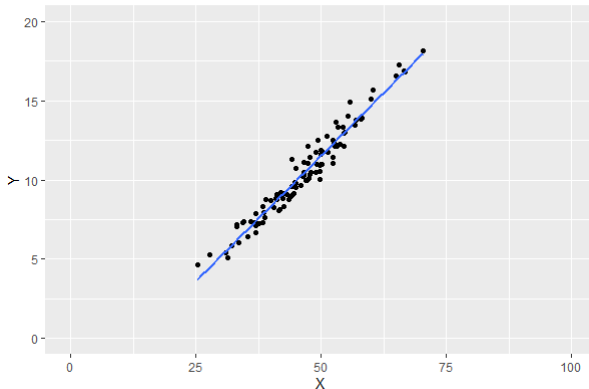
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Scatterplot for Y and X



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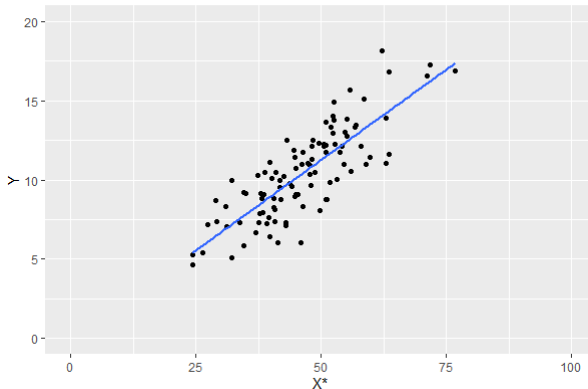
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Scatterplot for Y and X^* , where $X^* = X + U$, and $U \sim N(0, 5)$



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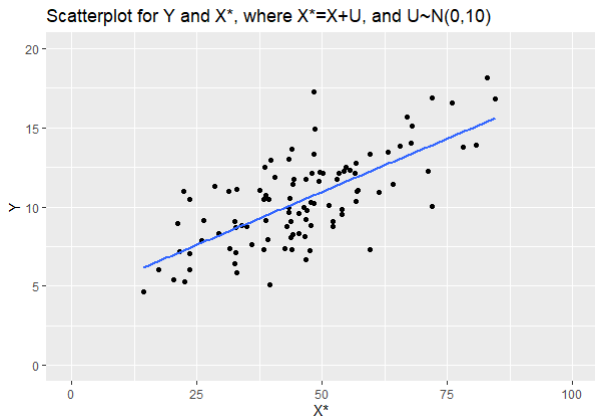
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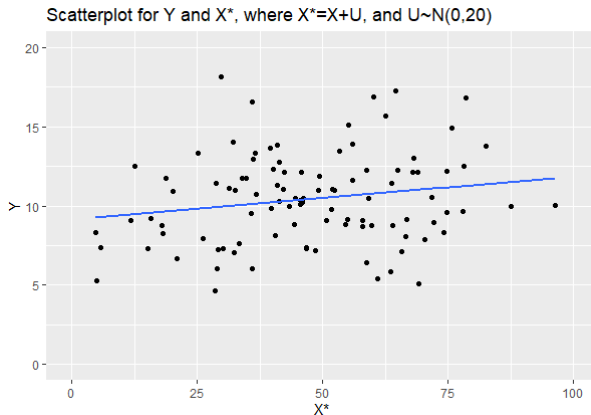
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- Scenario 3: systematic additive errors on the response
 - $Y^* = \alpha + \beta X + \epsilon$, with $Y^* = Y + U$, and $E(U) \neq 0$

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- Scenario 3: systematic additive errors on the response
 - $Y^* = \alpha + \beta X + \epsilon$, with $Y^* = Y + U$, and $E(U) \neq 0$

$$Y + U = \alpha + \beta X + \epsilon$$

$$Y = (\alpha - U) + \beta X + \epsilon$$
 - The constant is biased, but the slope is not

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- Scenario 3: systematic additive errors on the response

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- Scenario 4: systematic multiplicative errors on the response

- $Y^* = \alpha + \beta X + \epsilon$, with $Y^* = Y \cdot U$, and $E(U) \neq 1$

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- Scenario 3: systematic additive errors on the response

- $Y^* = \alpha + \beta X + \epsilon$, with $Y^* = Y + U$, and $E(U) \neq 0$

$$Y + U = \alpha + \beta X + \epsilon$$

$$Y = (\alpha - U) + \beta X + \epsilon$$

- The constant is biased, but the slope is not

- Scenario 4: systematic multiplicative errors on the response

- $Y^* = \alpha + \beta X + \epsilon$, with $Y^* = Y \cdot U$, and $E(U) \neq 1$

$$Y \cdot U = \alpha + \beta X + \epsilon$$

$$Y = \frac{\alpha + \beta X + \epsilon}{U}$$

- All regression coefficients are biased

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- Depending on the type of errors, we see vastly different impacts
 - From relatively negligible to ‘all is wrong!’
 - Even when the errors are completely random
- And we have only considered relatively simple scenarios

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Conclusion

- Depending on the type of errors, we see vastly different impacts
 - From relatively negligible to ‘all is wrong!’
 - Even when the errors are completely random
- And we have only considered relatively simple scenarios
- In the words of Nugent et al. (2000: 60):
 - *“Measurement error is, to borrow a metaphor, a gremlin hiding in the details of our research that can contaminate the entire set of estimated regression parameters”*



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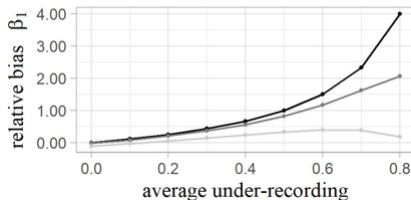
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- What happens when you use police data (subject to multiplicative, systematic and random errors) in linear regression?

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- What happens when you use police data (subject to multiplicative, systematic and random errors) in linear regression?

$$\text{worry} = \alpha + \beta_1 \text{crime}^* + \beta_2 \text{disorder} + \varepsilon$$



Random error: none, moderate (sd=0.04), substantial (sd=0.08)

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Conclusion

- What happens when you use police data (subject to multiplicative, systematic and random errors) in linear regression?
- One of our recommendations is to log-transform crime since
$$\log(X^*) = \log(X \cdot U) = \log(X) + \log(U)$$

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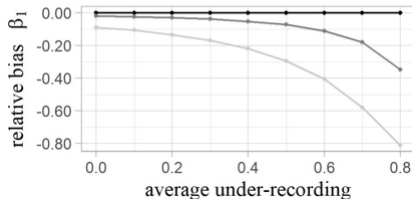
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Conclusion

- What happens when you use police data (subject to multiplicative, systematic and random errors) in linear regression?
- One of our recommendations is to log-transform crime since $\log(X^*) = \log(X \cdot U) = \log(X) + \log(U)$

$$\text{worry} = \alpha + \beta_1 \log(\text{crime}^*) + \beta_2 \text{disorder} + \varepsilon$$



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- We should always aim to improve data collection processes
- When that is not possible/sufficient we should adjust for the impact of measurement error

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Conclusion

- We should always aim to improve data collection processes
- When that is not possible/sufficient we should adjust for the impact of measurement error
- We have seen how in some simple settings we can anticipate - and therefore adjust - that impact
- When we can't trace out the impact of measurement error algebraically we need to use other methods

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- Most adjustment methods require additional forms of data
 - Multiple reflective indicators (latent variable models)
 - Instrumental variables (two stage processes)
 - A validation subsample (multiple imputation)
 - Repeated observations (regression calibration)

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Conclusion

- Most adjustment methods require additional forms of data
 - Multiple reflective indicators (latent variable models)
 - Instrumental variables (two stage processes)
 - A validation subsample (multiple imputation)
 - Repeated observations (regression calibration)
- Others can be used when all you have is an educated guess (sensitivity analysis)
 - Bayesian adjustments (Gustaffson, 2003)
 - Multiple overimputation (Blackwell et al., 2017)
 - SIMEX (Cook & Stefanski, 1994)
 - Simulations (the *RCME* package Pina-Sánchez et al., 2022)

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Conclusion

- We want to estimate the effect of collective efficacy on criminal damage rates, controlling for a few area characteristics
 - $\log(Y^*) = \alpha + \beta_1 X + \beta_k Z_k + \epsilon$
 - Population: 982 postcode areas in London
- We estimate it first using police data (naive model), and we re-estimate it using adjusted crime rates (sensitivity analysis)

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 - $\log(Y^*) = \alpha + \beta_1 X + \beta_k Z_k + \epsilon$
 - Population: 982 postcode areas in London
- We estimate it first using police data (naive model), and we re-estimate it using adjusted crime rates (sensitivity analysis)
- We simulate different combinations of measurement error to obtain multiple sets of ‘adjusted’ crime rates
 - We consider values for S (systematic error), R (random error), and D (differential errors)
 - which we derive from the Crime Survey for England and Wales
 - The measurement error term: $U = S + R + D \cdot X$
 - The adjusted crime rates: Y^*/U

The Naive Model

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	<i>outcome variable: log(criminal damage)</i>	
	Using police data	Adjusting for measurement error
constant	0.88***	
collective efficacy	-0.09***	?
% white British	0.11***	
% unemployed	0.14***	
median age	-0.12***	
R^2	0.23	
N	982	

- We re-estimate that model considering different errors
 - $S = (1, 0.86, 0.29)$
 - $R = (0.08, 0.1, 0.12)$
 - $D = (0, -0.1, -0.2, -0.3)$



The *RCME* Adjustment

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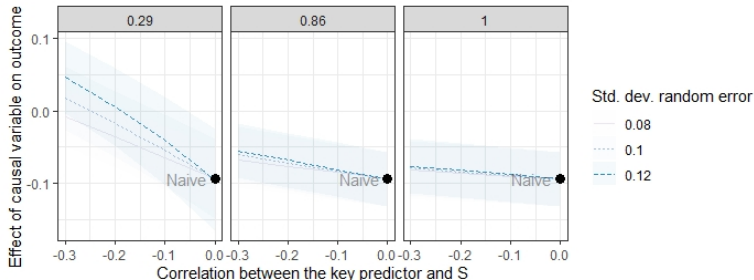
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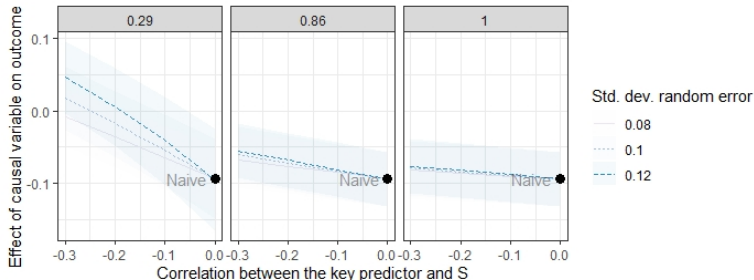
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- The effect size attributed to collective efficacy appears robust, unless...
 - in the presence of low recording rates, variable recording rates across areas, and some minor differential error
 - That is however the most likely scenario according to victimisation surveys

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- Many of the variables we use are affected by measurement error

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- Many of the variables we use are affected by measurement error
- Measurement error can bias univariate statistics but also associations with other variables perfectly measured
 - Even if the errors are random
 - The specific impact is hard to anticipate beyond simple scenarios

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Conclusion

- Many of the variables we use are affected by measurement error
- Measurement error can bias univariate statistics but also associations with other variables perfectly measured
 - Even if the errors are random
 - The specific impact is hard to anticipate beyond simple scenarios
- A much bigger problem than we tend to acknowledge
 - Affecting countless studies, potentially quite severely
 - And yet, we do very little about it

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- Many of the variables we use are affected by measurement error
- Measurement error can bias univariate statistics but also associations with other variables perfectly measured
 - Even if the errors are random
 - The specific impact is hard to anticipate beyond simple scenarios
- A much bigger problem than we tend to acknowledge
 - Affecting countless studies, potentially quite severely
 - And yet, we do very little about it
- Besides improving data collection processes, we also need to employ adjustments methods
 - Many require additional data, others are quite complex
 - But there are a few methods (e.g. simulations) that are simple enough, and can be used even as a sensitivity analysis tool

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Thank you!

